

Position Sensitive Scintillation Detector for Gamma Spectroscopy

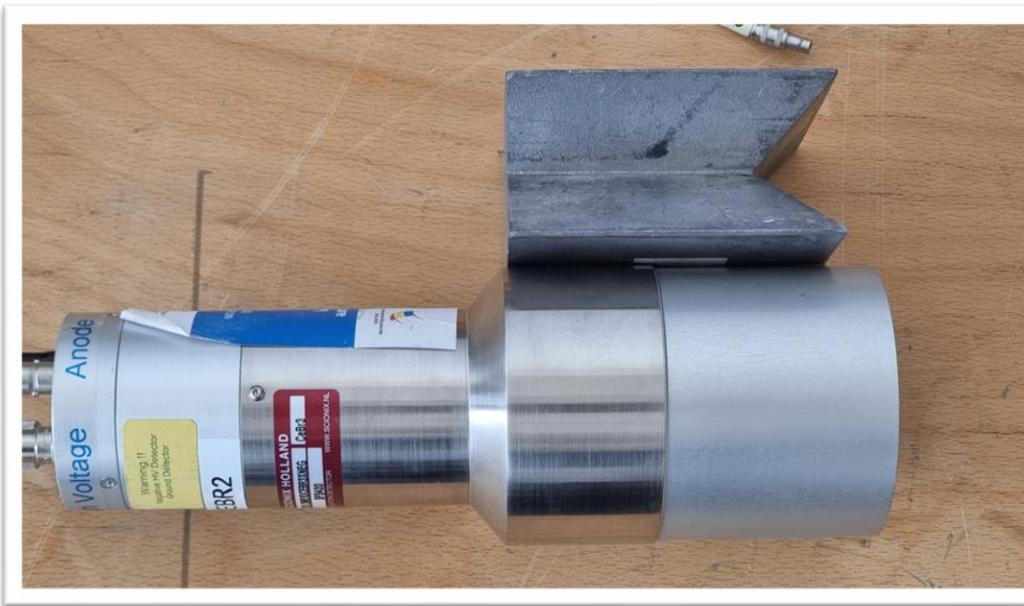
BOGDAN OCTAVIAN TEMELIE

SCIENTIFIC COORDINATORS: DR. GABRIEL V. TURTURICĂ, DR. VIOLETA IANCU

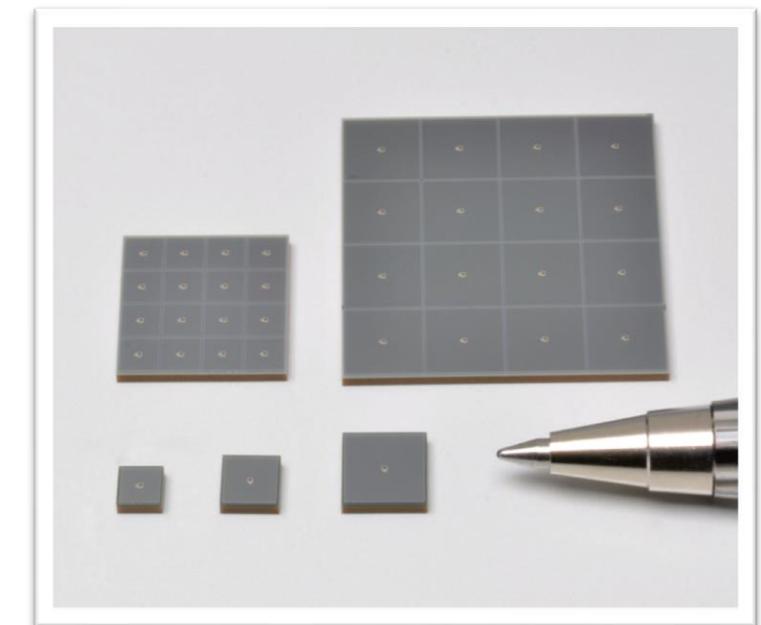
Main idea and Motivation

- Scintillation detectors - scintillation crystal paired with a photomultiplier tube
- Information about gamma counts, energy and timing but not interaction location
- Too large setups for positioning with regular photomultiplier tubes

- Use of Silicon Photomultipliers (SiPM) to reduce scale of setups
- Use of SiPMs to determine particle interaction location
- SiPMs – small size, low operating voltage, less sensitive to magnetic interference



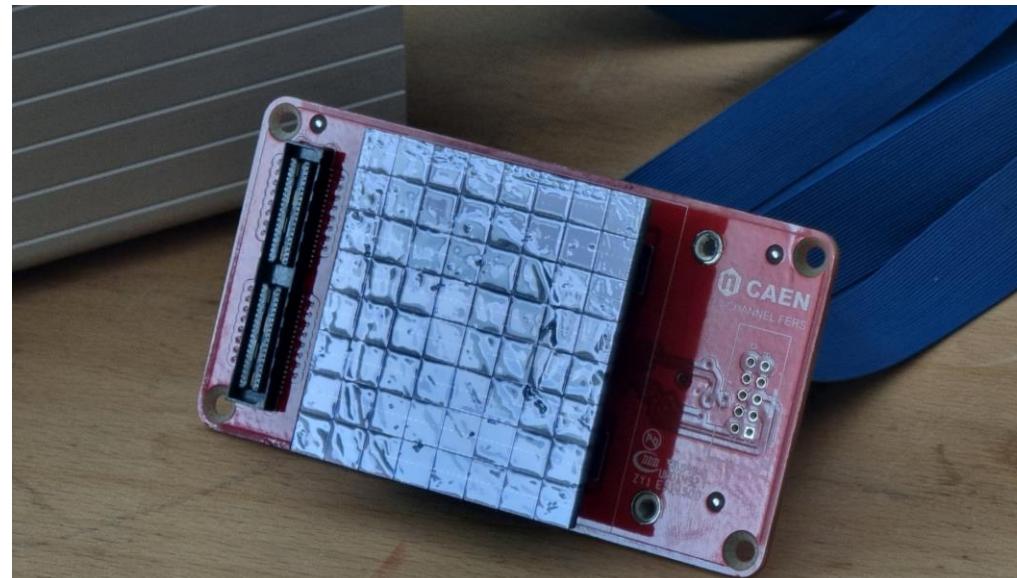
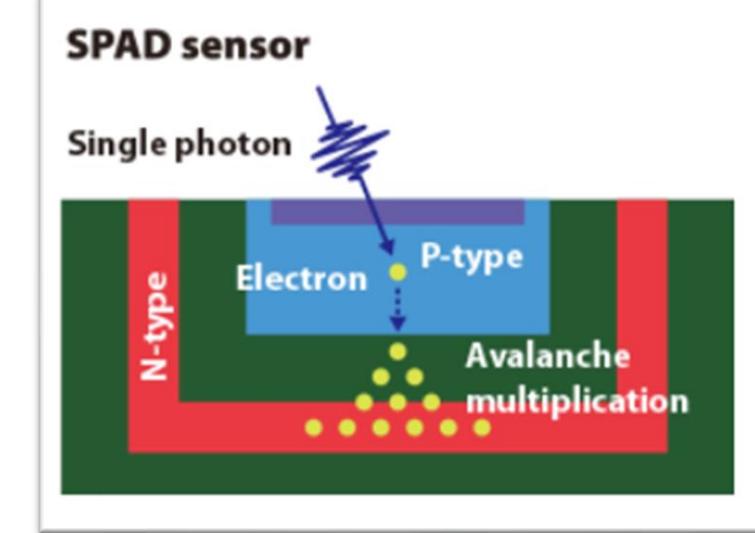
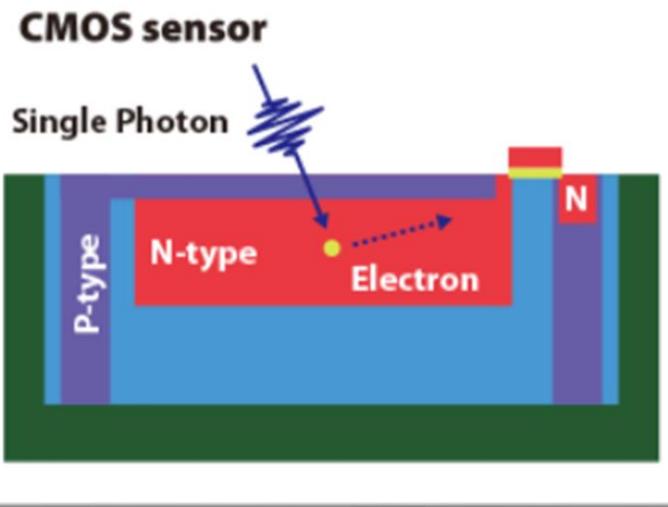
CeBr₃ scintillation detector,
PMT a few cm across



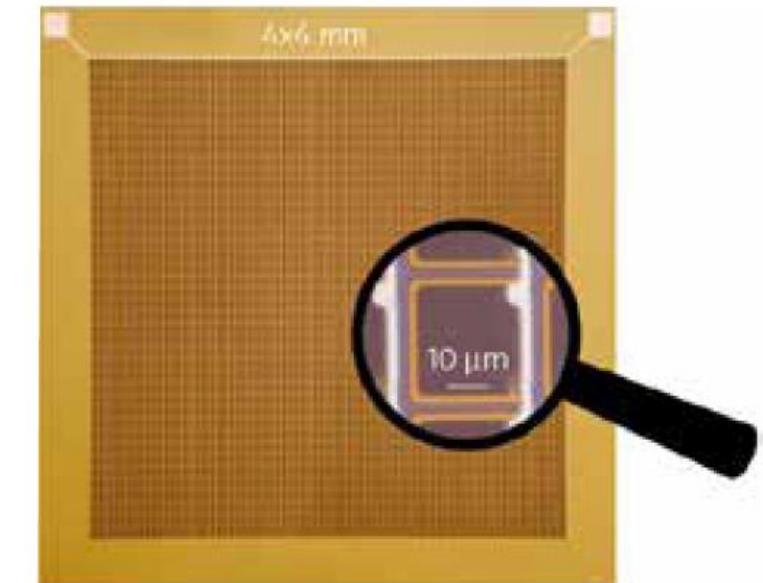
Multiple size SiPMs,
a few mm² in area

How do SiPMs work?

- Made of many SPADs (Single-Photon Avalanche Diodes).
- SPADs allow photon counting
- Similar to a regular photography camera



The 8x8 matrix of SiPMs used



4x4mm SiPM made of many 10 μ m SPADs

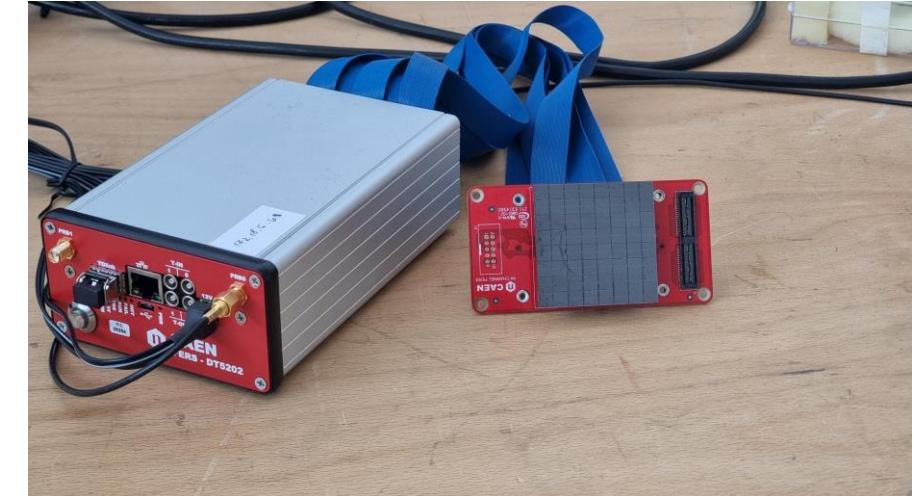
Construct and characterize a position-sensitive
detector using an 8x8 SiPM array and a thin,
flat CsI crystal

Detector construction

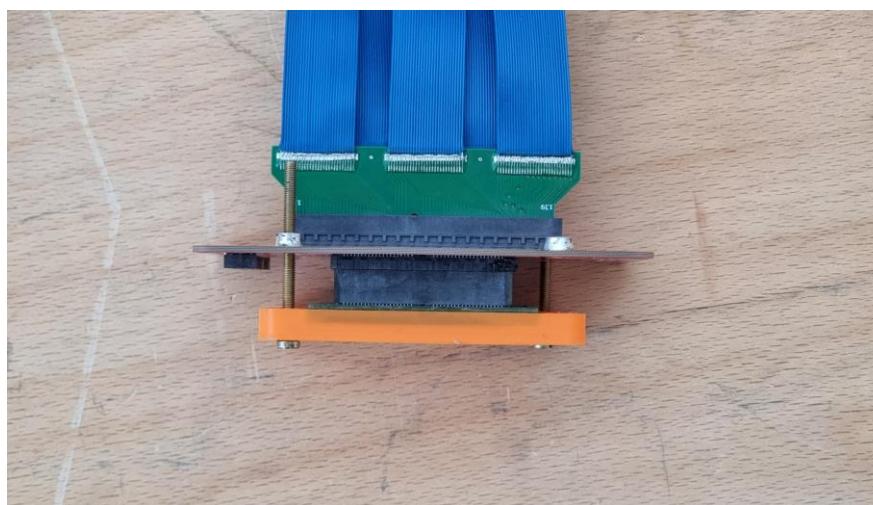
- CsI scintillator paired with an 8x8 SiPM array
- Encasing for stray photon prevention
- Electronic module to collect data from each SiPM



Cylindrical and flat scintillation crystals



Connected 8x8 SiPM array

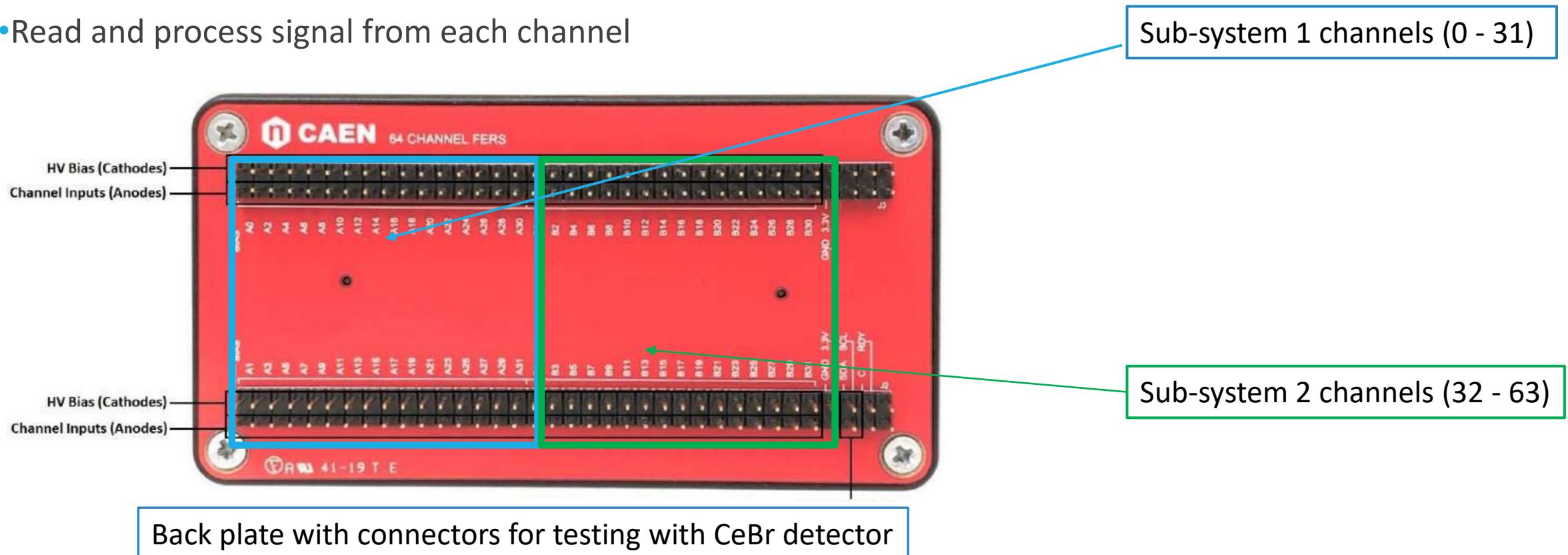


The flat scintillator installed



Detection assembly

- Electronic module with two sub-systems, each handling 32 channels
- Control the voltage applied to each channel (SiPM)
- Read and process signal from each channel



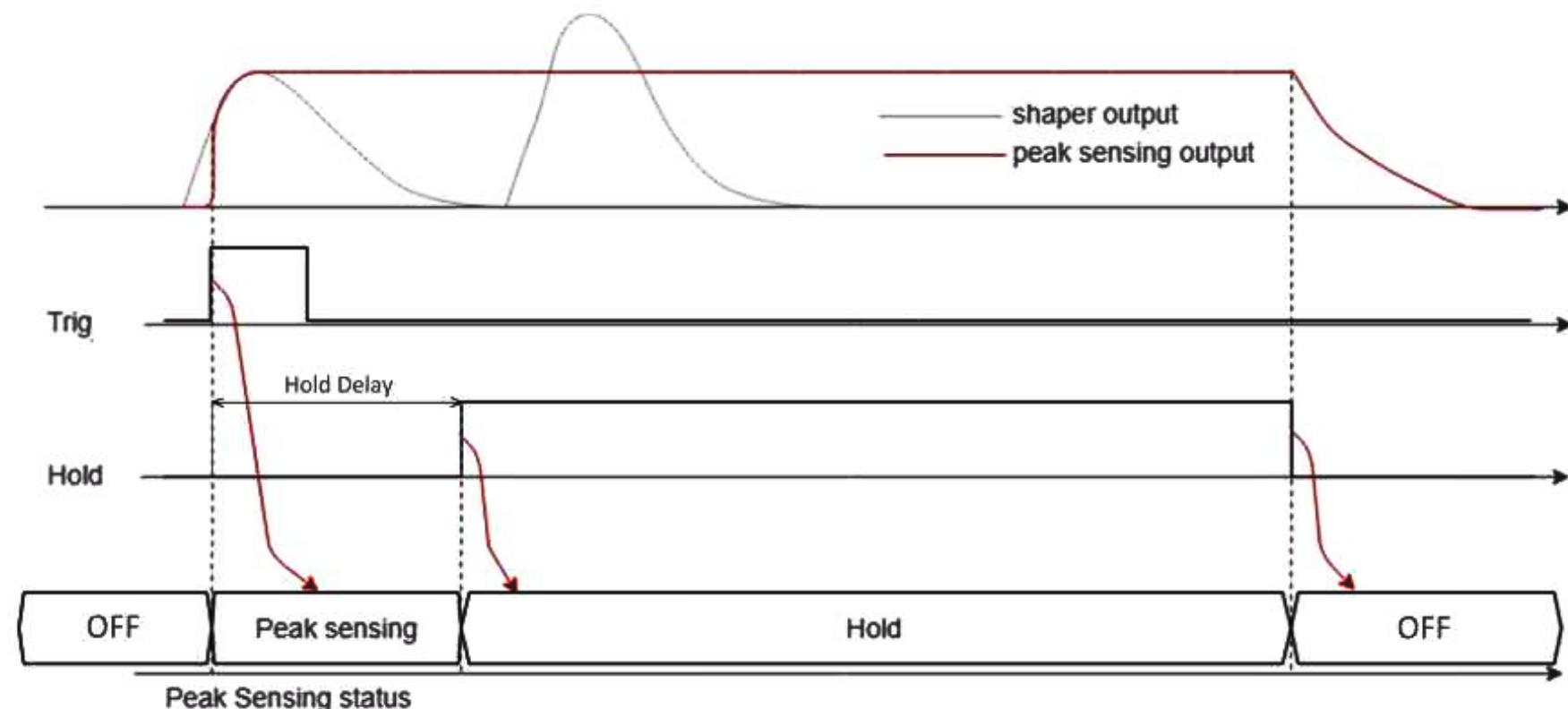
- SiPM signal = number of incident photons -> use of algorithms suitable to reconstruct interaction position

Peak sensing

Two parameters control the processing of signals from SiPMs:

- Shaping time: controls time constant of the input signal
- Hold delay: time interval between the trigger start and hold signal

- Off phase: peak detector is off
- Peak sensing phase: when the trigger arrives, the peak detector holds the amplitude
- Hold phase: no other input signal is detected, the peak detector is disconnected from the input source

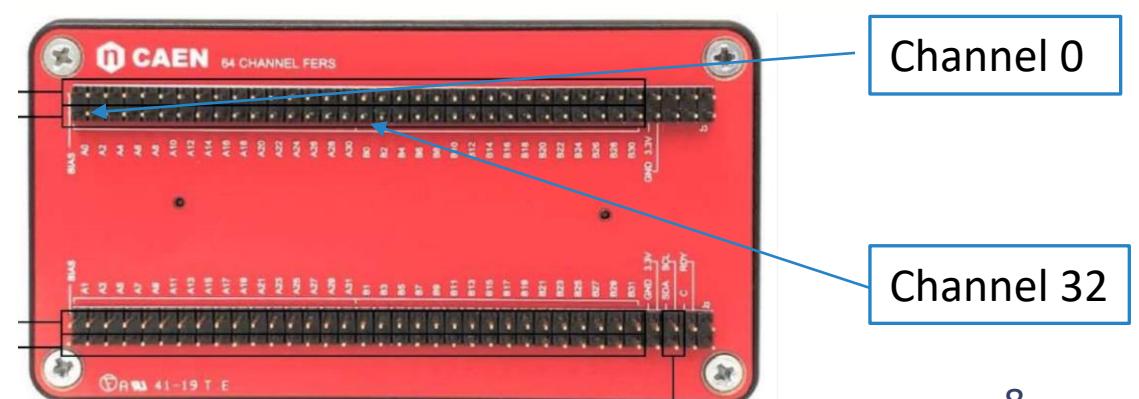
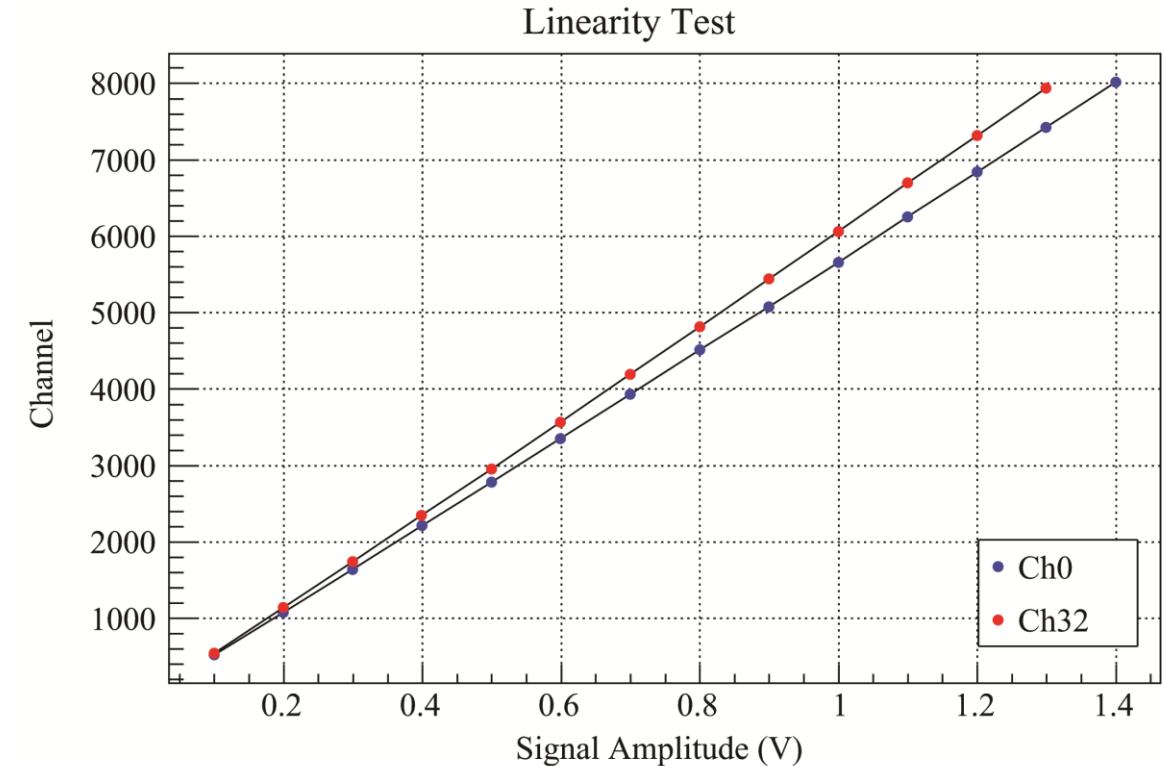


Initial Tests

- Linearity of channels
- Hold delay optimization
- Addback optimization

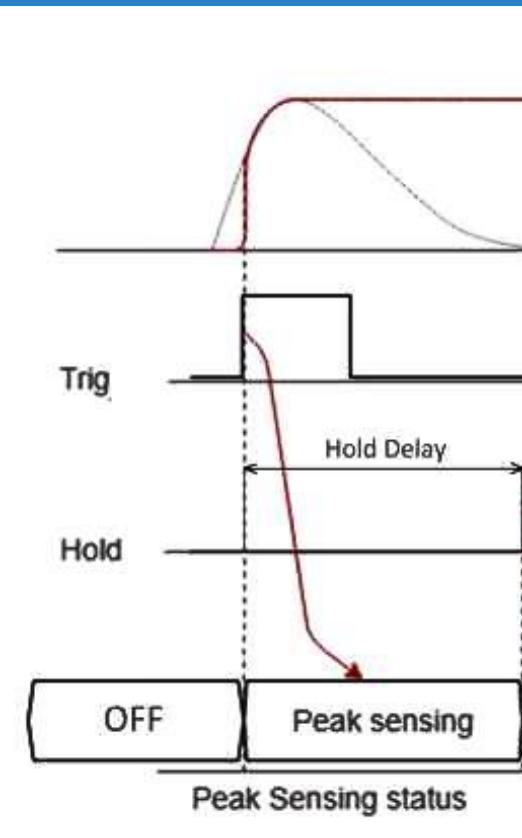


- Linearity test
- Pulse generator for signals with varying amplitudes (0.1V to 1.5V)



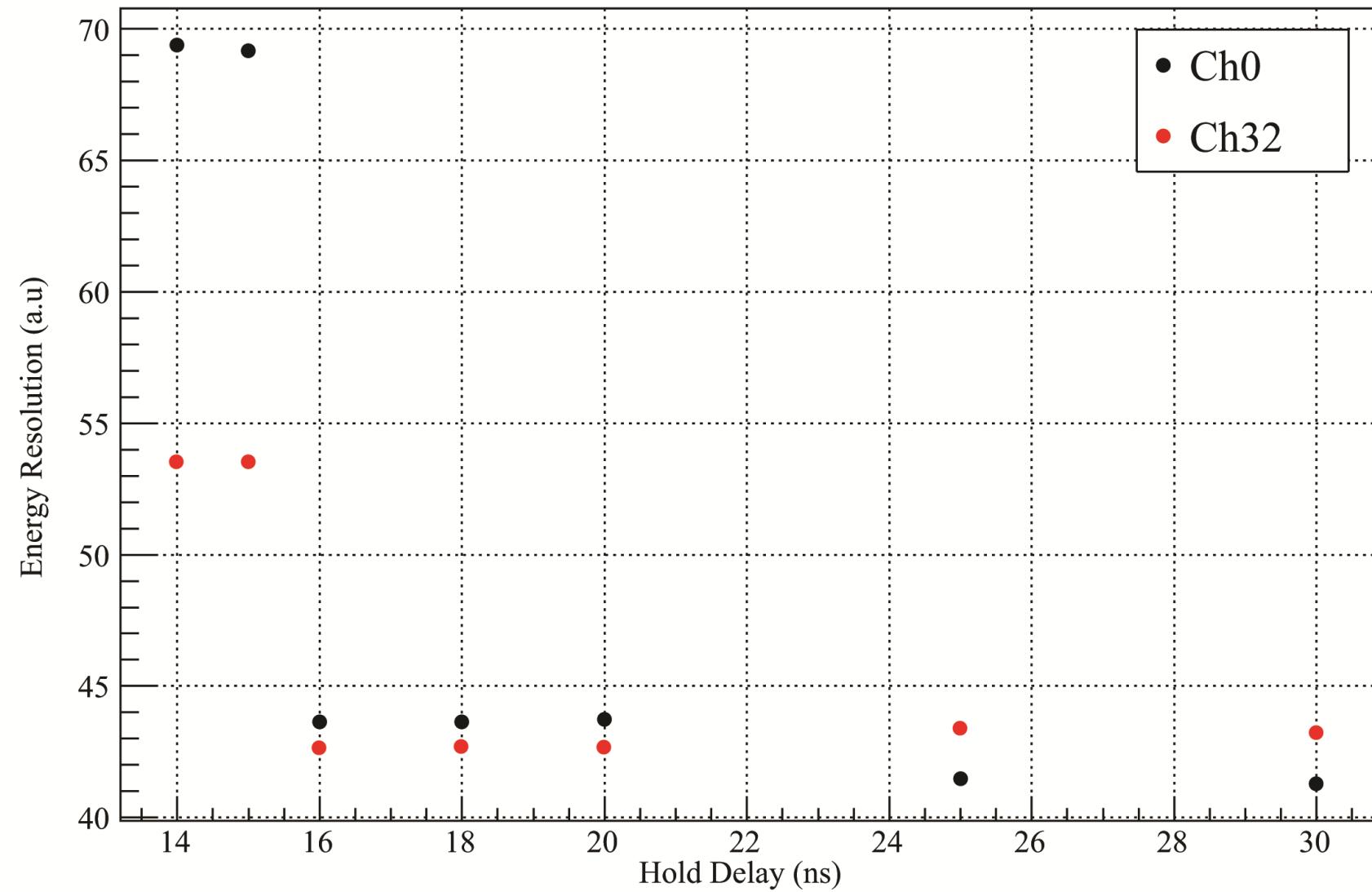
Initial Tests

- Linearity of channels
- Hold delay optimization
- Addback optimization



- Hold Delay influence on energy resolution for each sub-system

Hold Delay Test

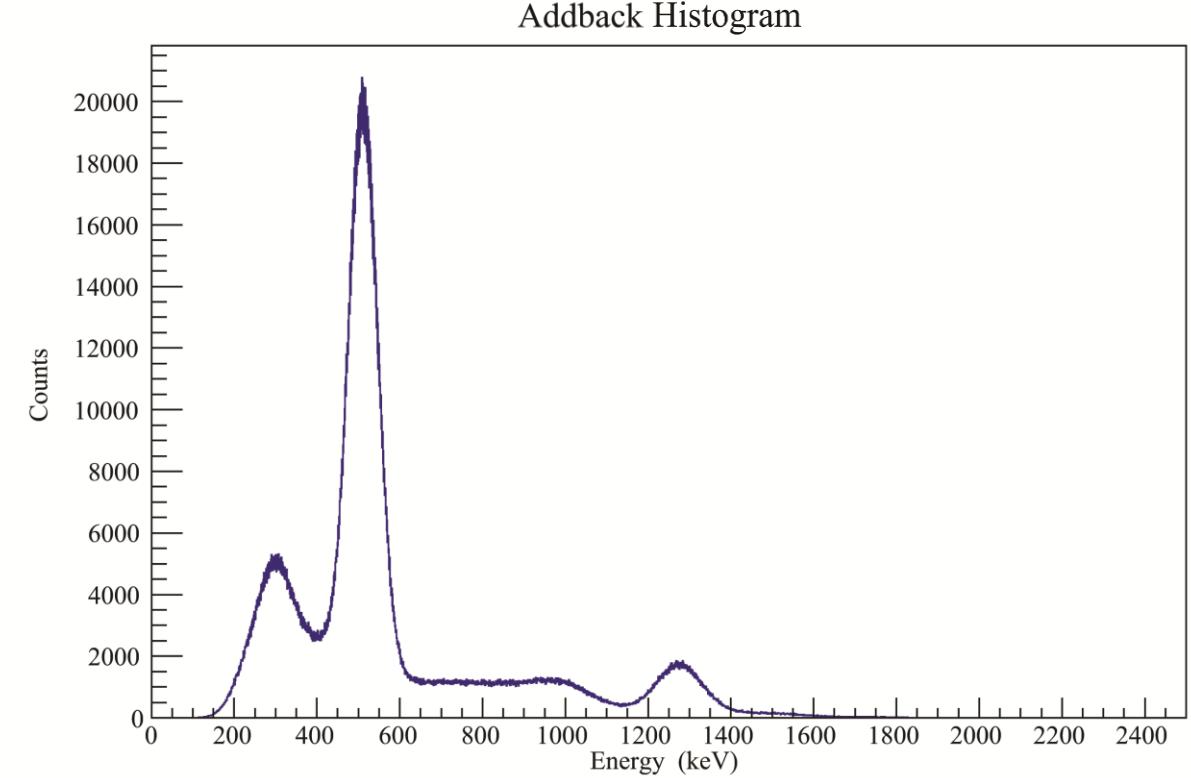
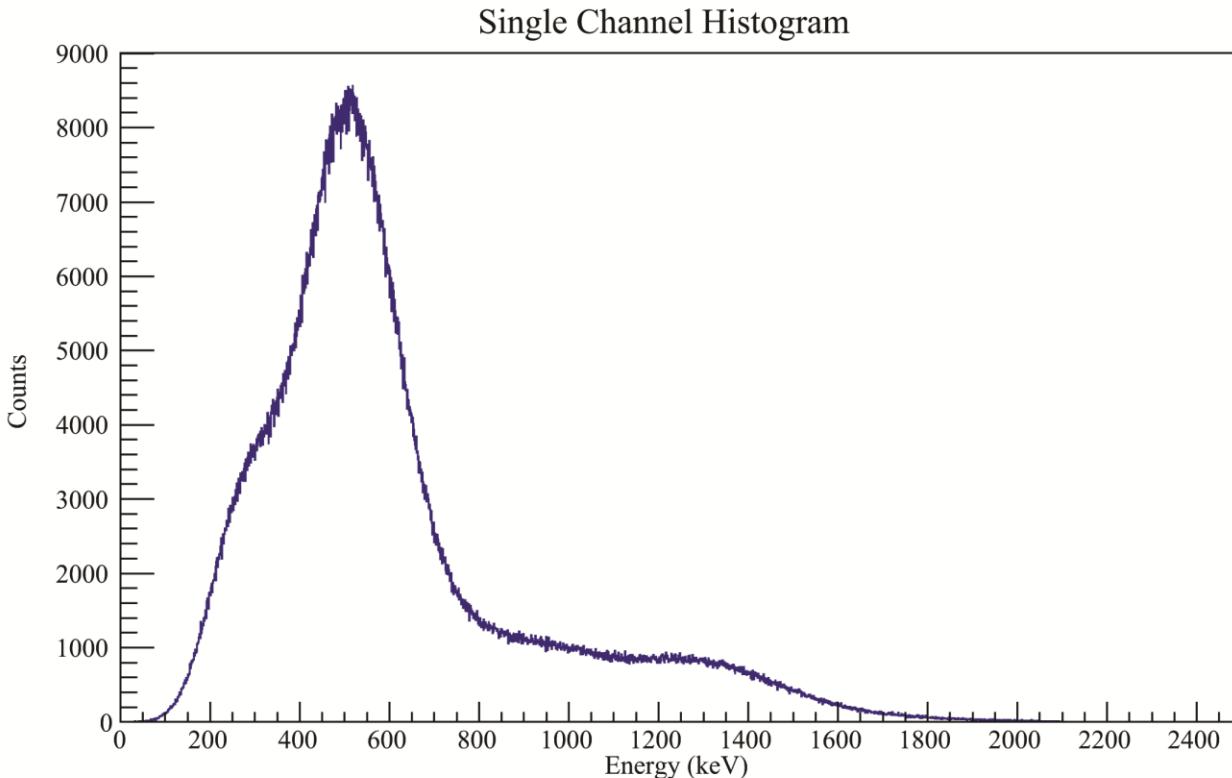
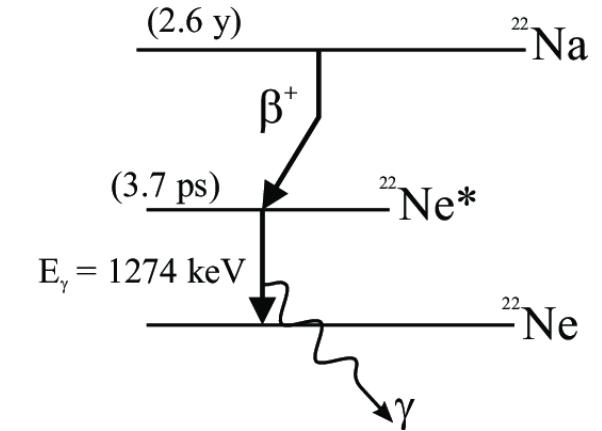
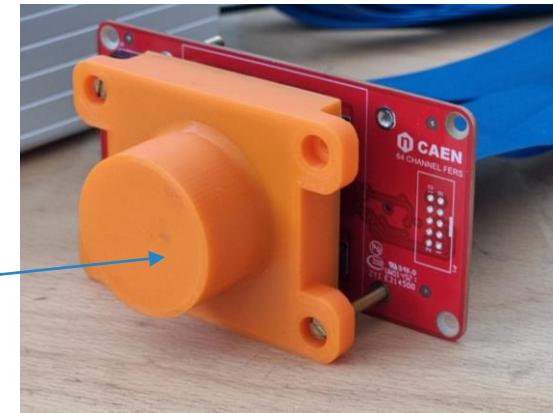


Initial Tests

- Linearity of channels
- Hold delay optimization
- Addback optimization

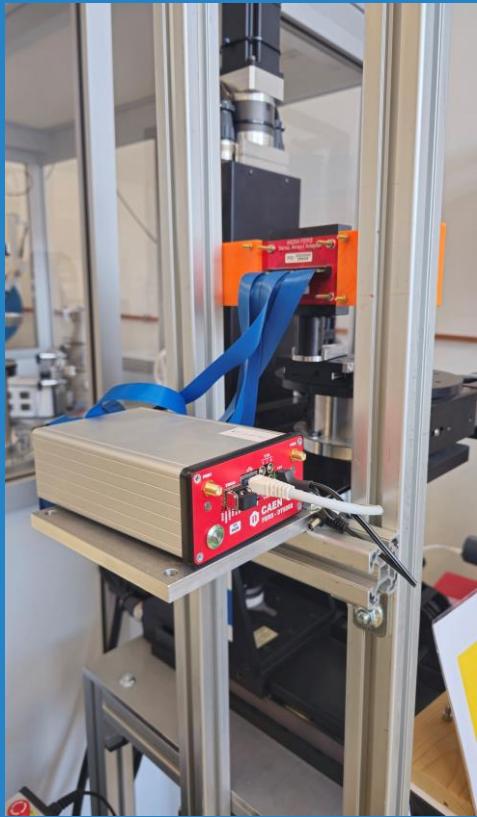
- Addback – sum data from multiple channels
- ^{54}Mn (834 keV), ^{22}Na (511 keV) and ^{137}Cs (661 keV), for calibration
- Addback on ^{22}Na to reveal 1274 keV gamma peak

Scintillator covers
16/64 channels



Interaction position measurements

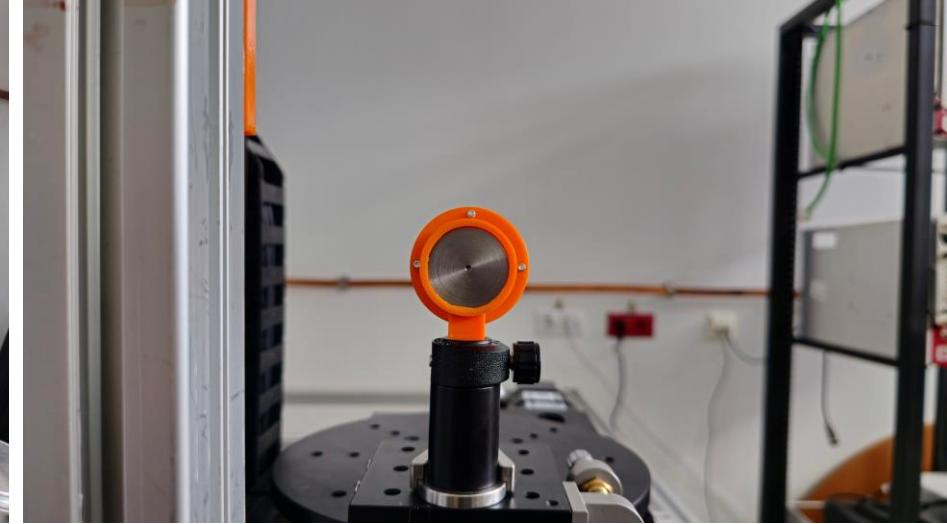
- Measurements setup
- Data processing



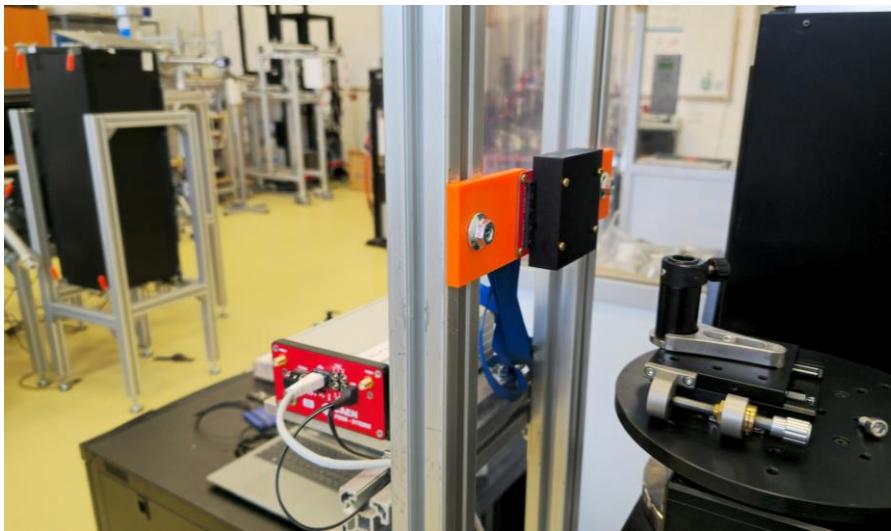
Detection assembly



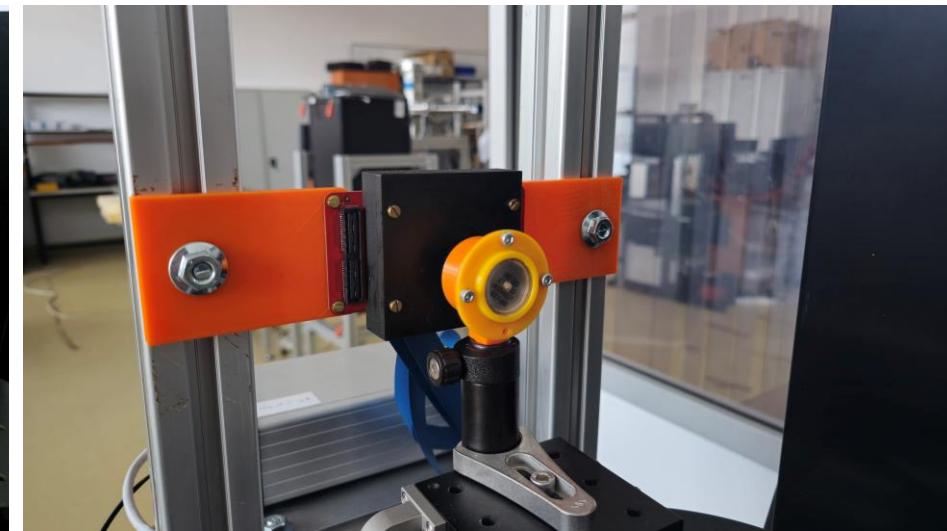
General overview of the setup



Densimet collimator with ^{241}Am source



Scintillator (2mm thick) and SiPM package



Example of interaction position measurement

Interaction position measurements

- Measurements setup
- Data processing

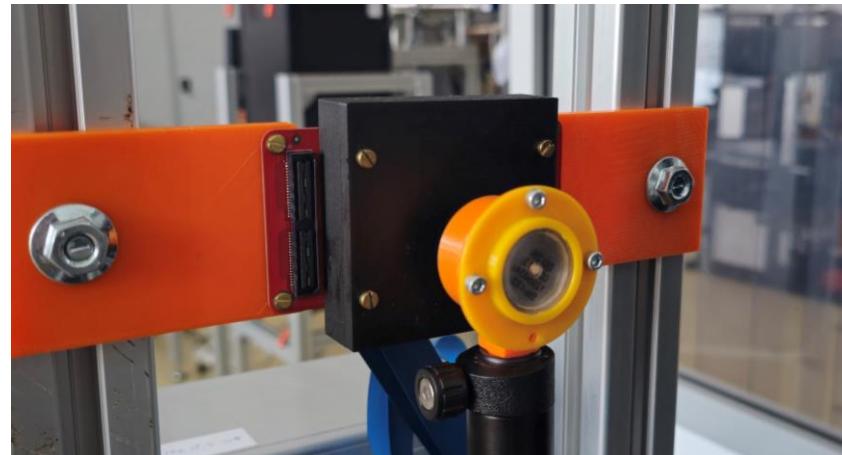
1. Measure point on matrix



2. Record individual gamma events

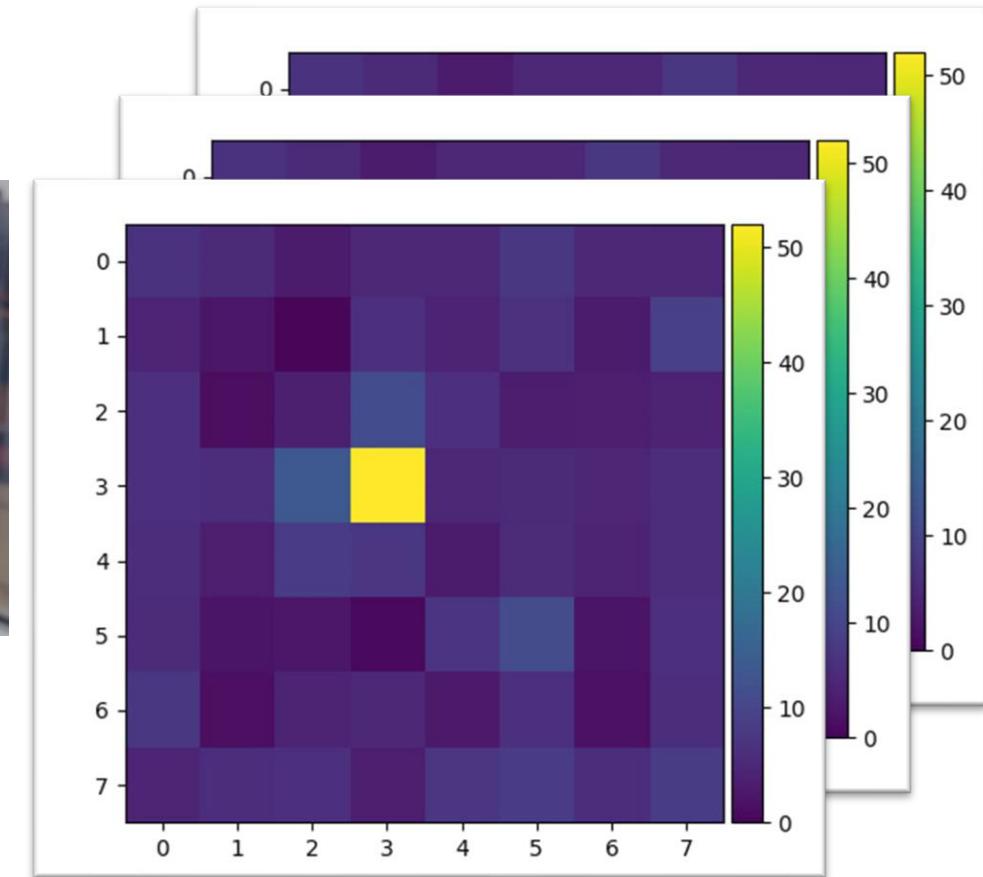


3. Construct individual intensity maps



Individual point measurement

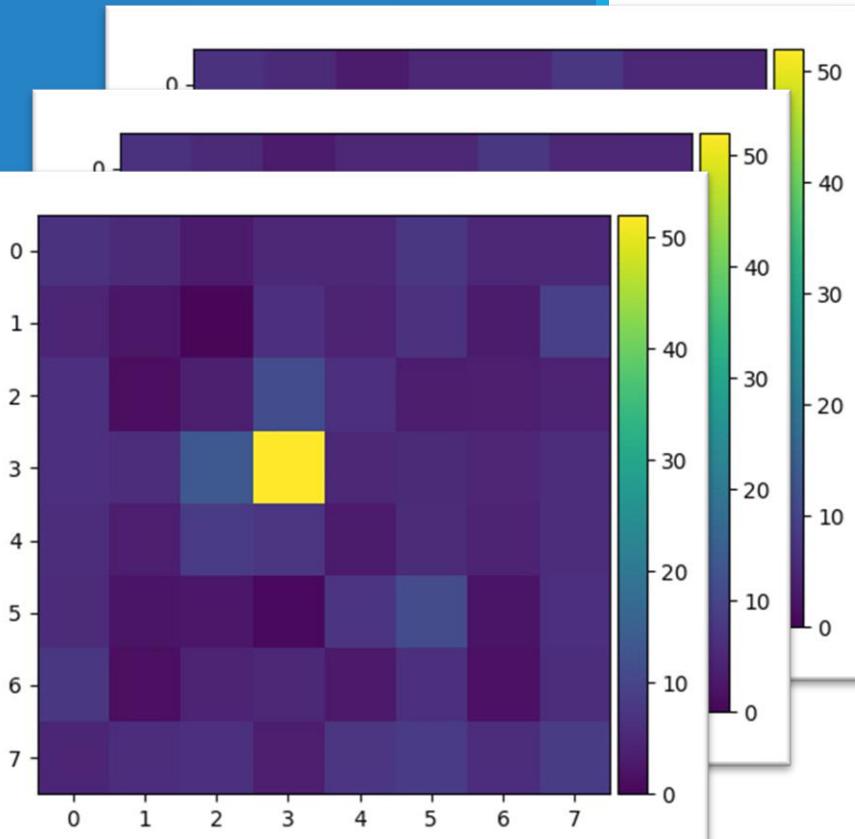
- An 8 x 8 matrix of points measured on the detector
- One measured point -> many single gamma events recorded
- Higher energy gamma -> more scintillation light -> higher intensity recorded



Single gamma events

Interaction position measurements

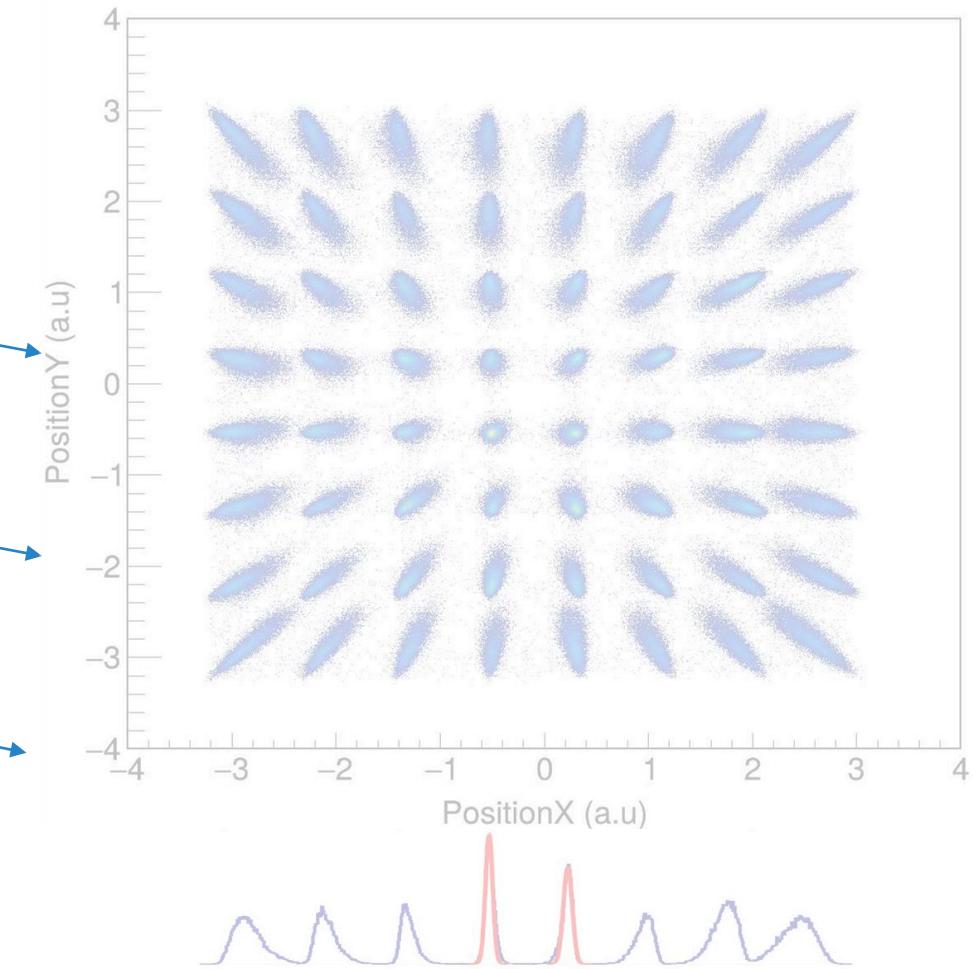
- Measurements setup
- Data processing



- Single events processed using Centre of Gravity algorithm (CoG):

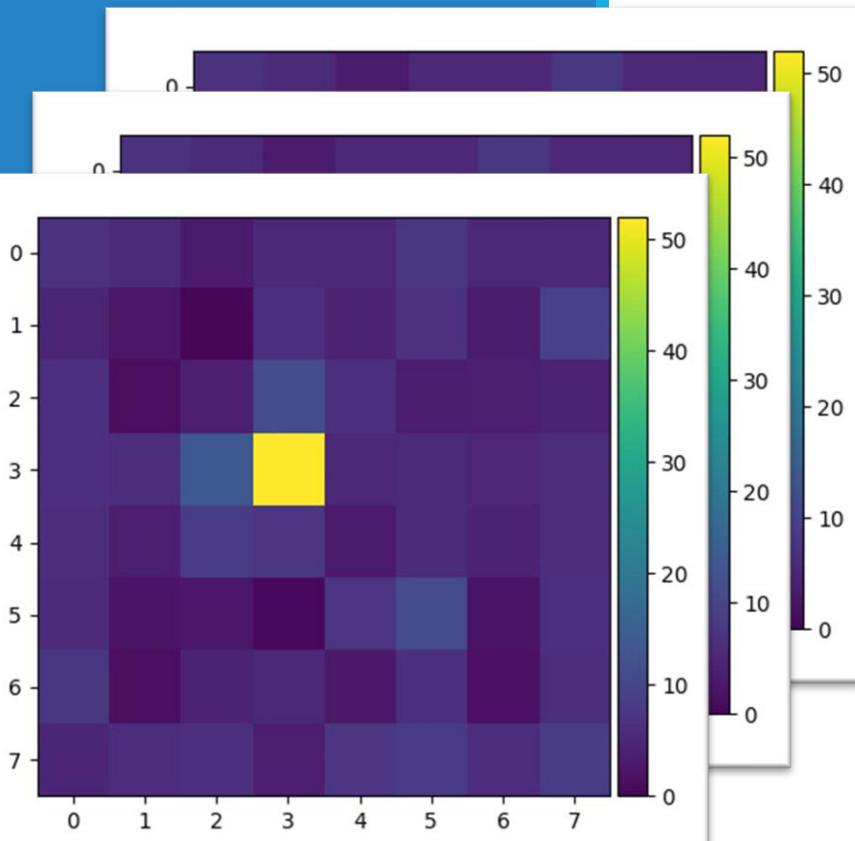
$$x_{int} = \frac{\sum_{i=1}^{64} q_i^2 \cdot x_i}{\sum_{i=1}^{64} q_i^2}$$

$$y_{int} = \frac{\sum_{i=1}^{64} q_i^2 \cdot y_i}{\sum_{i=1}^{64} q_i^2}$$



Interaction position measurements

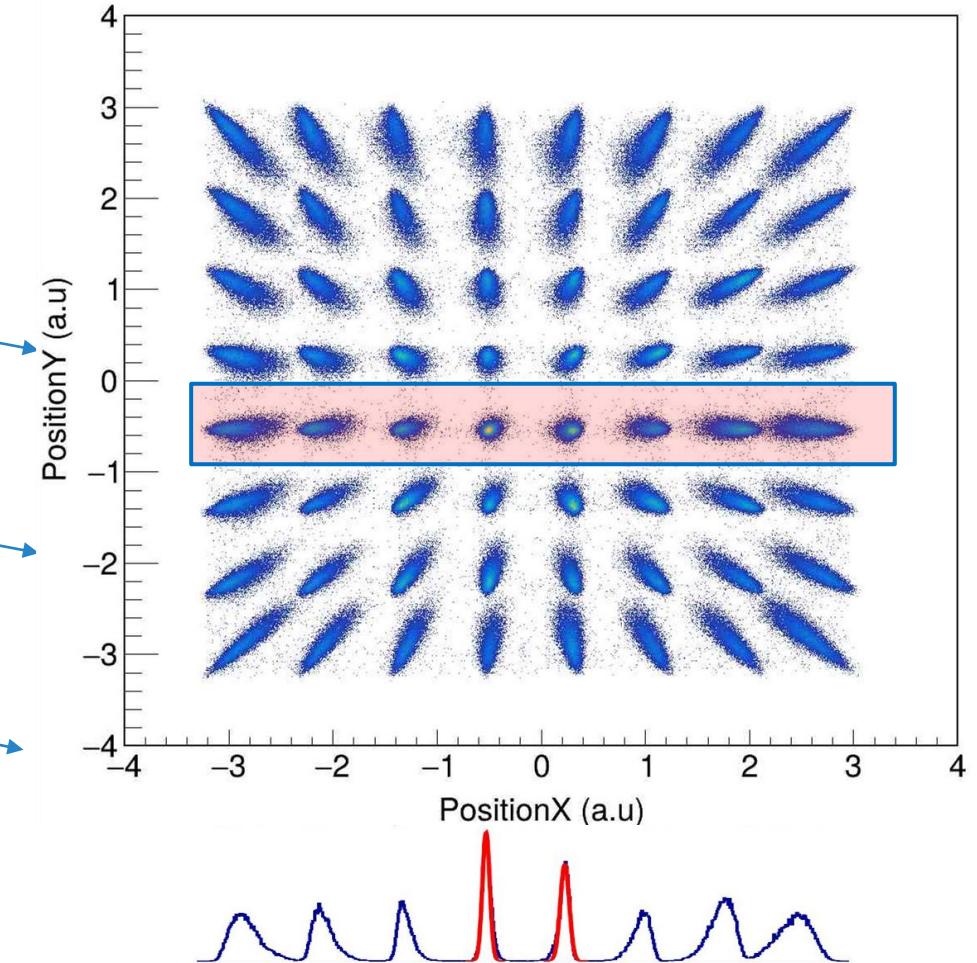
- Measurements setup
- Data processing



- Single events processed using Centre of Gravity algorithm (CoG):

$$x_{int} = \frac{\sum_{i=1}^{64} q_i^2 \cdot x_i}{\sum_{i=1}^{64} q_i^2}$$

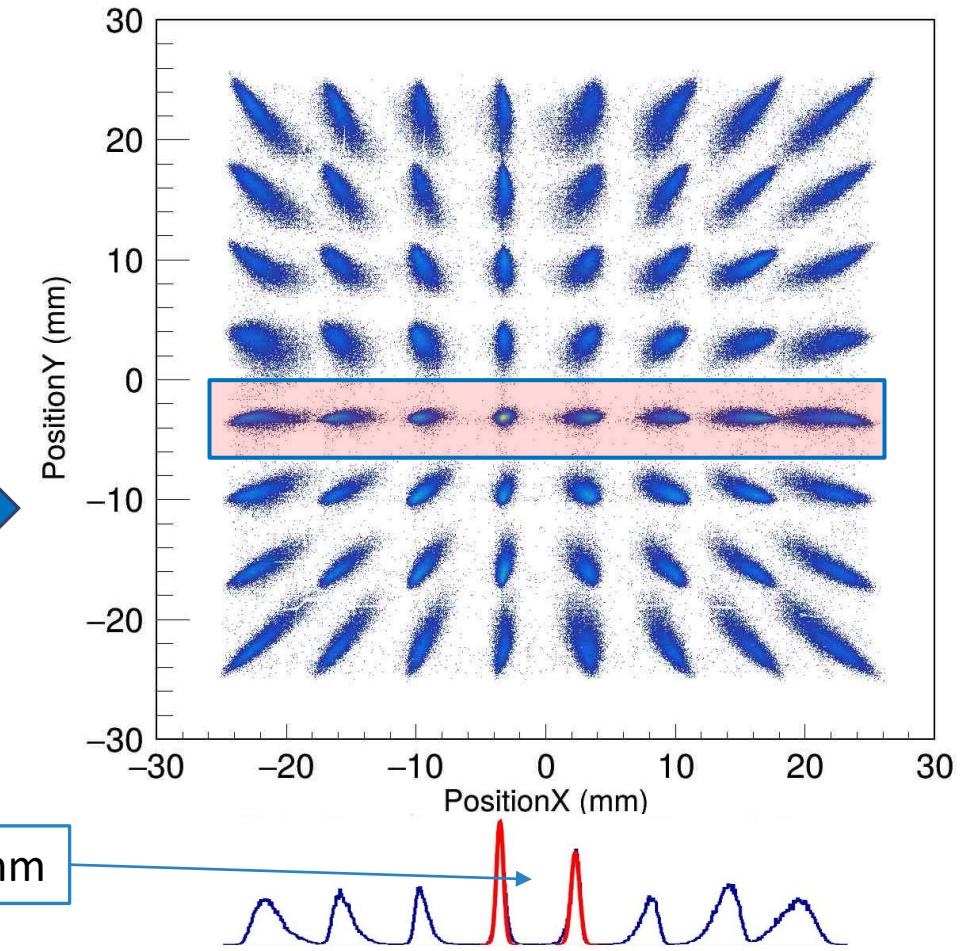
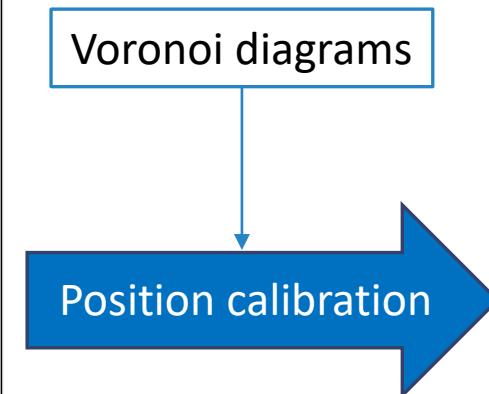
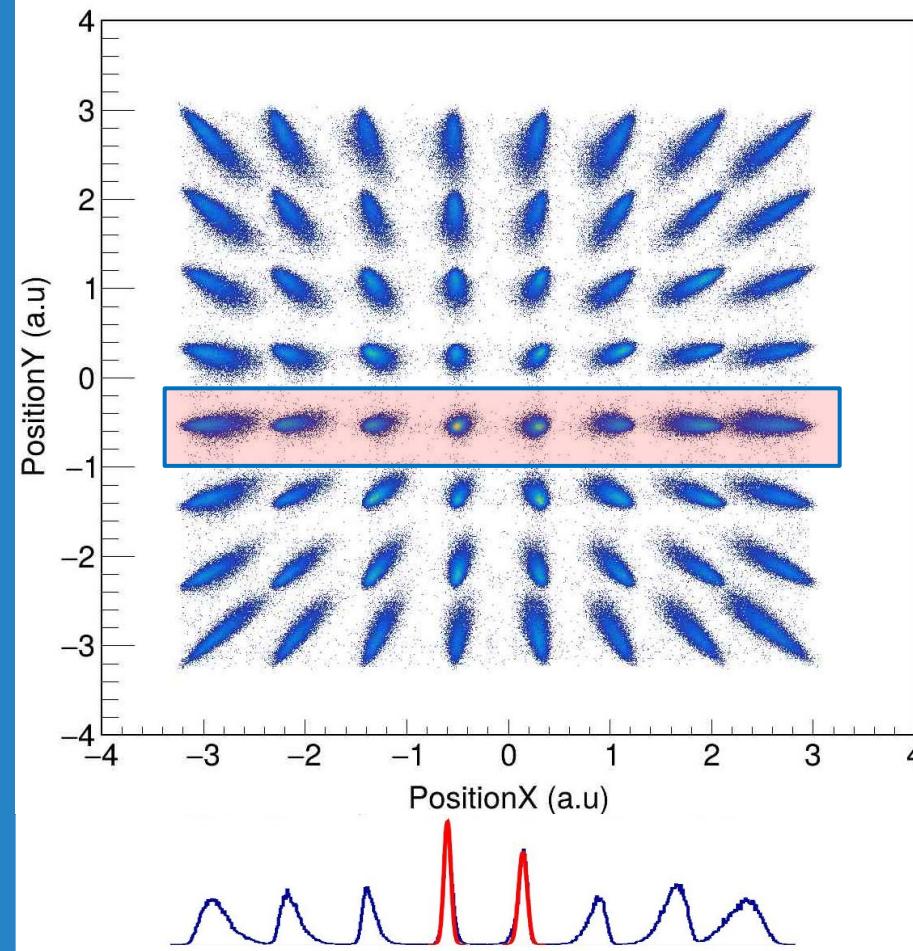
$$y_{int} = \frac{\sum_{i=1}^{64} q_i^2 \cdot y_i}{\sum_{i=1}^{64} q_i^2}$$



Interaction position measurements

- Measurements setup
- Data processing

- Voronoi diagrams used for position calibration
- Centre of pixels calculated with experimental data correlated to physical coordinates on the detector



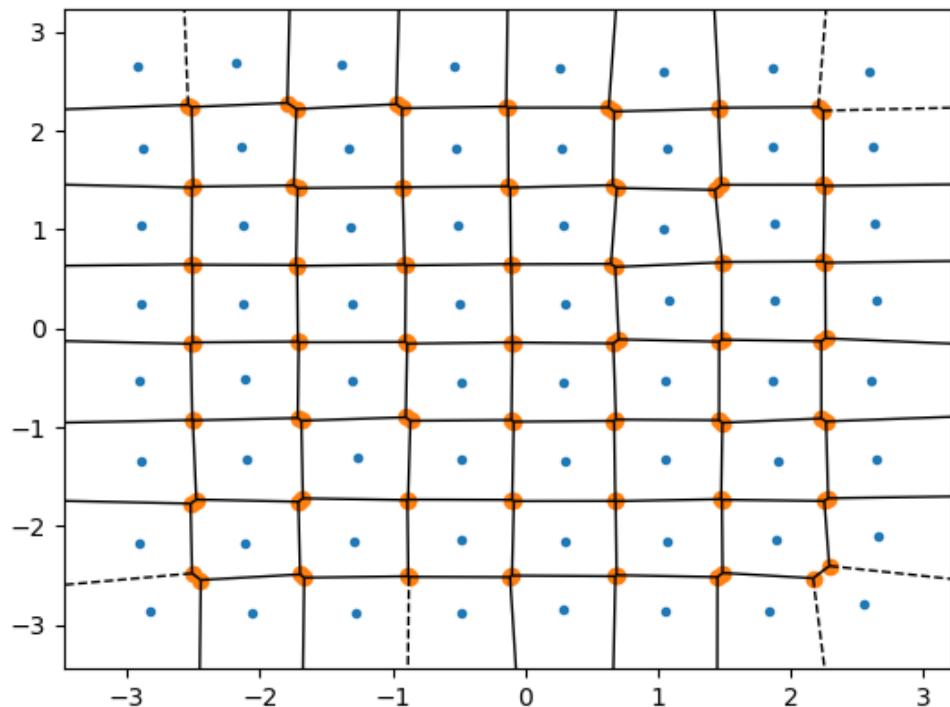
Conclusions and Future plans

- Initial tests run successfully
- Addback procedure works effectively
- Potential to be used as position sensitive detector
- Future plans
 - Develop algorithms to correct the skewness of spots on the positioning histogram
 - Further development to accomodate larger scintillators

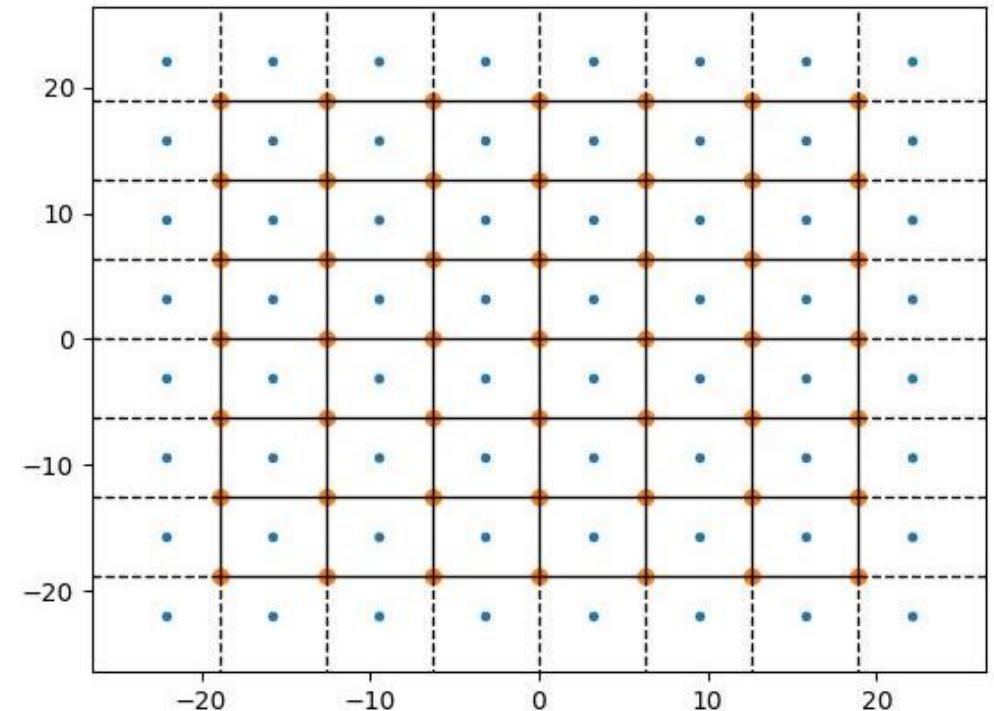
Thank you for your attention!

Voronoi Diagrams

- Region of Interest (ROI) -> points closest to one site (pixel centre) -> one site generates one ROI



Voronoi diagram constructed with experimental data



Voronoi diagram constructed with physical coordinates